The Simulation and Assimilation of Doppler Wind Lidar Observations in Support of Future Instruments

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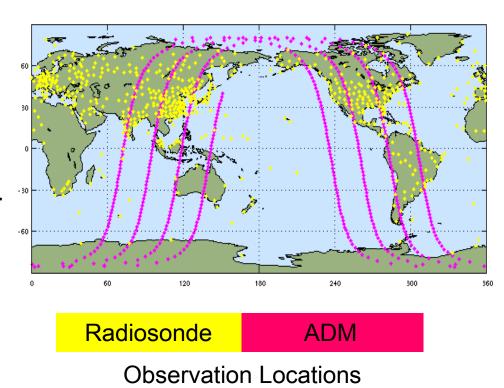
R. Errico, R. Yang, M. McGill, S. Palm, R. Gelaro, M. Rienecker

Introduction

- Importance of Wind Measurements
 - Global wind profiles are "essential for operational weather forecasting on all scales and at all latitudes"
 - World Meteorological Organization (1996)
- Atmospheric Winds from the ground
 - Global Rawinsonde Record
 - Ground-based, remotely sensed wind observations
 - Mainly in data rich regions
- Atmospheric Winds from Space
 - Atmospheric Motion Vectors (AMVs) and Scatterometers

Introduction to Doppler Wind Lidar

- The Doppler Wind Lidar Concept
 - Lidar backscatter is Doppler shifted by a scattering agent
 - Improved accuracy in height assignment
- Spaceborne Doppler Wind Lidar
 - Global, 3D measurements of wind
 - NASA 3D-Winds (NRC Decadal Survey recommendation)
 - Full horizontal wind
 - ESA ADM-Aeolus (2012)
 - single horizontal wind component



w1

wrmccart, 4/30/2010

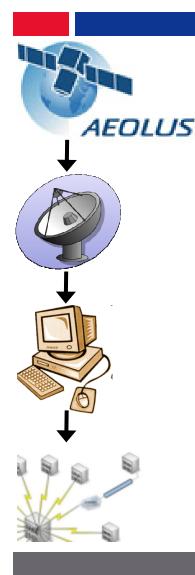
ADM-Aeolus

- Direct-Detection technique (355 nm)
 - Vertical single-component profiles in clear sky (Rayleigh)
 - Higher quality
 measurements in presence
 of scattering agent (Mie)
- Orbit Characteristics
 - 408 km
 - Dawn-dusk
 - Sun-synchronous



- Viewing Geometry/Sampling
 - 90° off-track (away from sun)
 - 7 second measurements (~50 km)
 - One measurement every 200 km

ADM-Aeolus Pre-Assimilation Data Flow Chart



Downlink

Location: Svalbard

Latency

Near-Realtime: 3 hr

Quasi-Realtime: 30 min

Processing & Distribution

- L1B distributed in NRT by ESA via GTS
- L2B product will be produced by ECMWF (IFS)
 - NRT modeling centers will have to run L2B processing independently
 - Best scientific methodology due to first-guess dependency

ADM-Aeolus Pre-Launch Data Flow Chart

- Prior to launch, realistic data for system preparedness
 - Establish a realistic dataset for data assimilation system development
 - Local Proxy Data
 - Generated using OSSE framework
 - Purpose of this effort is not to "sell" instrument (already sold)
 - Establish a realistic end-to-end flow to test mechanics of system
 - NRT Proxy Data
 - To be considered closer to launch

Data Assimilation

Variational Cost Function:

$$J(x) = (x - x_b)^{T} B^{-1}(x - x_b) + (y - H[x])^{T} R^{-1}(y - H[x])$$

When minimized,

$$x = x_a$$
 (analysis state)

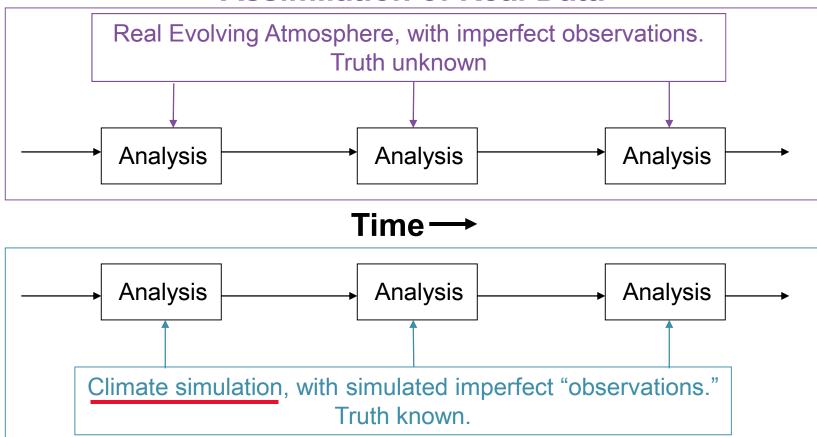
- H[x] transforms the atmospheric state to observation space
 - Currently, H[x] is a projection of the winds to line-of-sight space
 - Upon launch, H[x] will include L2B processing

OSSE for ADM Preparedness

- There is no predecessor for spaceborne DWL
- Sources of proxy data
 - Ground-based instruments
 - Inadequate spatial sampling
 - Adapt existing spaceborne measurements
 - Completely different in nature than spaceborne DWL
 - Simulated Observations
 - Can be simulated anywhere
 - If done properly, they can contain all of the necessary characteristics to best emulate real data:
 - Spatial and vertical sampling
 - Yield
 - Error characteristics

What is an OSSE

Assimilation of Real Data

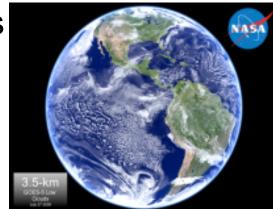


Observing System Simulation Experiment (OSSE) (R. Errico)



The "Real" Atmosphere

- In an OSSE, an atmospheric model is run in a climate (free-running) mode
 - This is the Nature Run (NR)
- The behavior of this atmosphere is essential to the process
 - Though artificial, it needs to be realistically chaotic

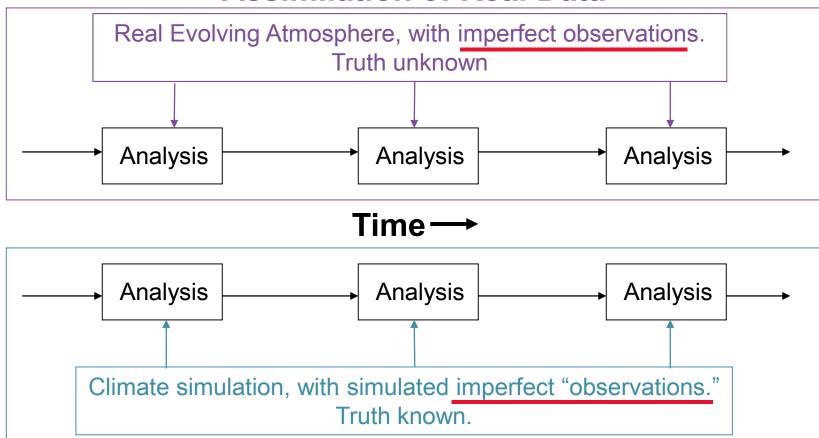


3.5 km GEOS-5 Climate Simulation

- It is the truth
- Current Nature Run Joint OSSE Nature Run
 - T511 ECMWF 13 month model run spawned in May 2005
- Future Nature Run GMAO/GEOS-5 Hi-res Nature Run

What is an OSSE

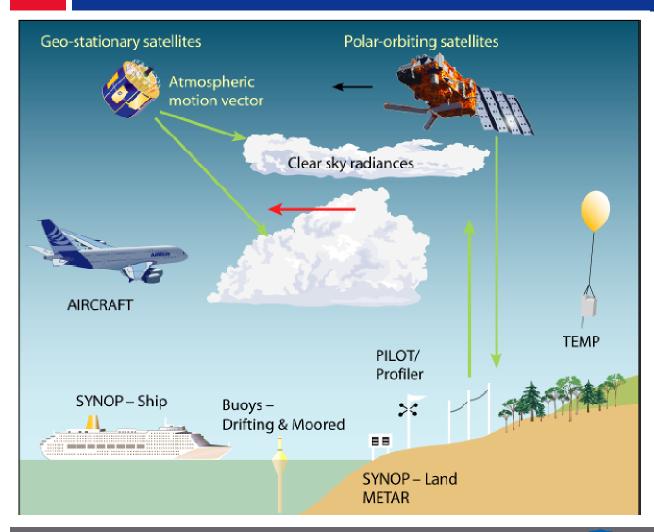
Assimilation of Real Data



Observing System Simulation Experiment (OSSE) (R. Errico)



Simulating Observations



- Six million+
 observations are
 assimilated
 globally, daily
 - Most observations are from satellites
- A successful
 OSSE requires
 realistic fake
 observations

Figure via ECMWF

Simulating a Realistic Observing System

- The analysis solution (minimized cost function) can be written as $\mathbf{x} = \mathbf{x_b} + \mathbf{K} [\mathbf{y} H(\mathbf{x}_b)]$
- In an OSSE, your observations are

$$\mathbf{y} = H_z(\mathbf{z}) + \mathbf{e}$$

- The validity of a simulated observation network is dependent on the errors
 - Simulated observation errors (e) need to account for
 - Instrument noise
 - Observation contamination (data yield, i.e. clouds, precipitation)
 - Representativeness (sub-gridscale variability)

- Simulation of ADM is dependent on key fields
 - Backscatter & extinction from the atmosphere, clouds, and aerosols
 - 3D wind field
- Only the wind field is inherent to the nature run
 - Molecular/Rayleigh backscatter f(T,p)
 - Cloud backscatter/extinction f(Cloud Fraction, CLWC, CIWC)
 - Aerosol backscatter/extinction
 - Not inherent to NR
- ADM measures at a scale finer than that of the NR
 - Need to account for sub-gridscale variability
- The DJF season of the NR is compared to the seasonally corresponding CloudSat/CALIPSO (CS/CAL) record

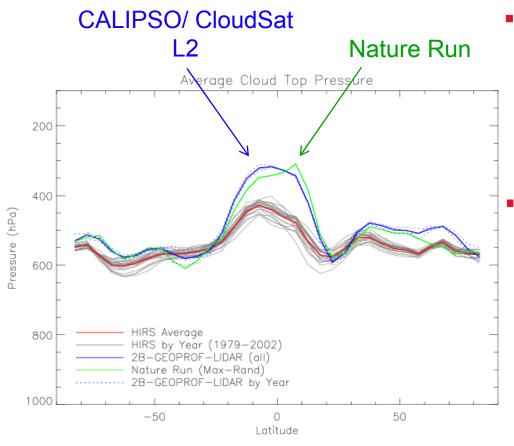
Comparing NR Clouds to CloudSat/CALIPSO

- Only cloud fraction is considered
- CS/CAL
 - Level 2B GEOPROF-LIDAR product
 - 1 km resolution along-track, reports up to five cloud layers
 - Only consider highest vertical cloud

NR

- A maximum-random overlap scheme implemented for subgridscale variability
 - Adjoining model levels to have maximum overlap
 - If two clouds exist in a vertical column with clear-sky between them, random overlap is assumed
 - Sampling the same as one season of the CS/CAL data
- Comparisons are made in 5° bins

Clouds in the Joint OSSE Nature Run



Importance of clouds

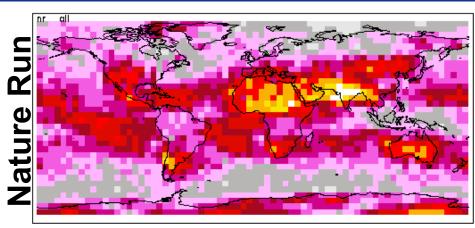
- The top of a cloud can act as a scattering agent
- Optically thick clouds limit wind retrievals

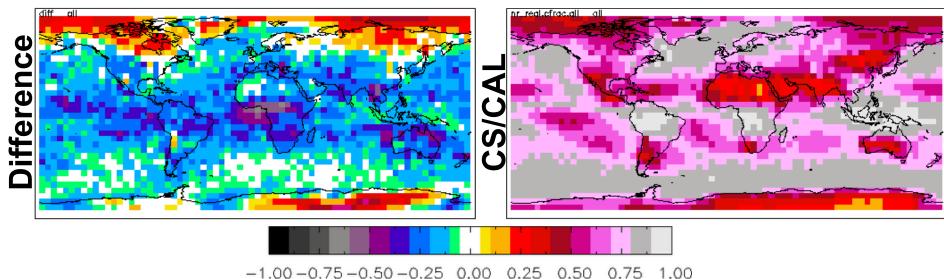
Placement of clouds

- Realistic vertical placement of clouds
- NR underestimates cloud amount
 - ~12% globally
 - Related to measurement yield

Clouds in the Joint OSSE Nature Run

- Cloud Fraction for all clouds
- Clear lack of clouds in NR





Aerosols in the Joint OSSE Nature Run

- Importance of aerosols
 - Aerosols act as a scattering agent
- Placement of aerosols
 - Not available in the NR
 - Traditionally taken from a climatological background
 - Inconsistent with atmospheric state
 - Dynamically consistent aerosol fields
 - Unique GSFC effort
 - GOCART aerosol transport model embedded in the GEOS-5 model
 - Aerosol fields forced by the meteorology of the Nature Run

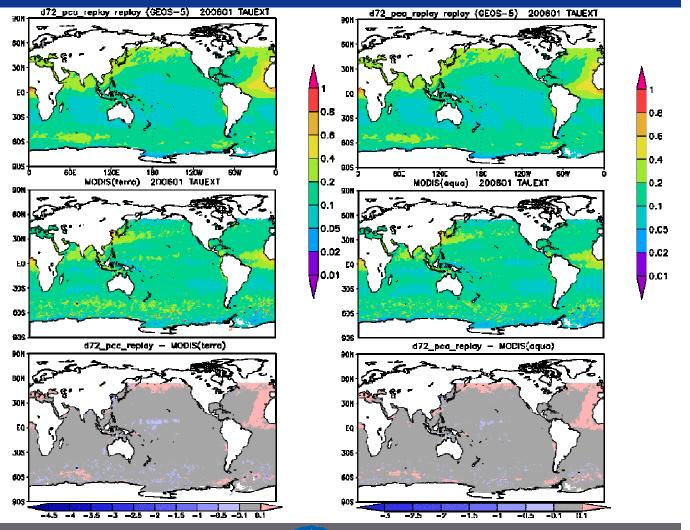
Aerosol Validation

- Replay aerosols compared to MODIS (Aqua and Terra, separately) and MISR
 - NR sampled at MODIS/MISR retrievals for consistency
 - Clear sky, daytime only
- Showing January of the Nature Run versus real January 2006

Aerosol Validation



- Aqua (right)
- NR (top)
- MODIS (middle)
- NR MODIS (bottom)



(R. Govindaraju)

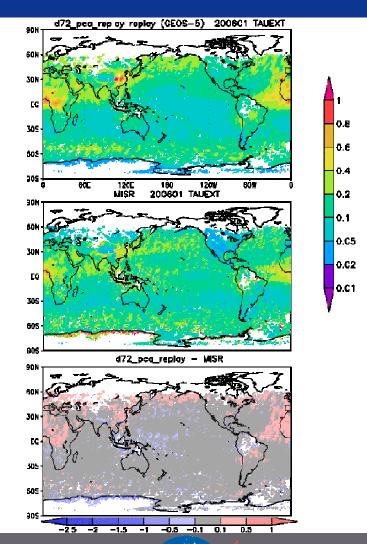


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Goddard Space Flight Center National Aeronautics and Space Administration

Aerosol Validation

- NR (top)
- MISR(middle)
- NR MISR (bottom)



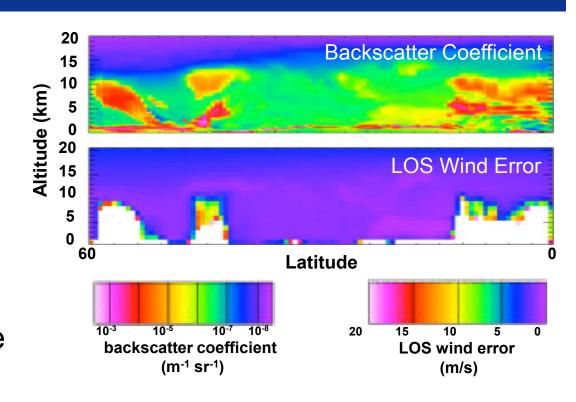
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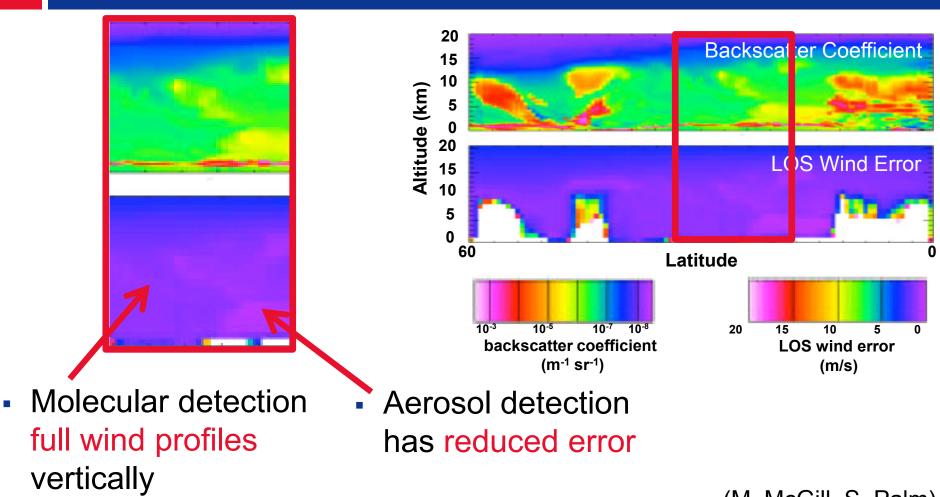
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- Simulated from a modeled atmospheric state
- Errors increase with height
- Clear-Sky backscatter coefficient and line-ofsight wind error are inversely proportionate
- Clouds degrade measurement quality

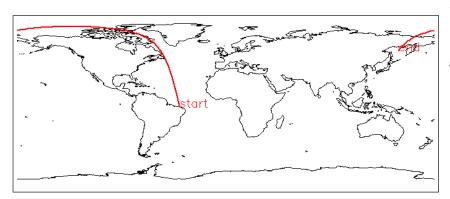


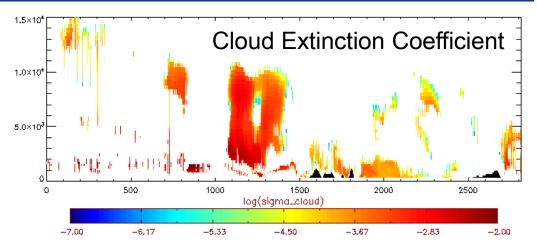
(M. McGill, S. Palm)

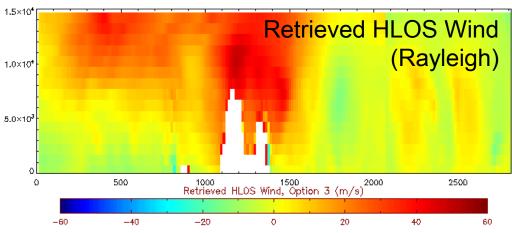


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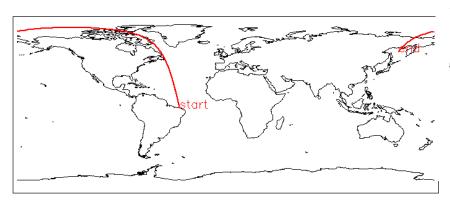
- Simulated ADM measurements
 - Nature Run
 - LIPAS
 - ADM Simulator developed at KNMI
 - Not run in "Burst Mode"

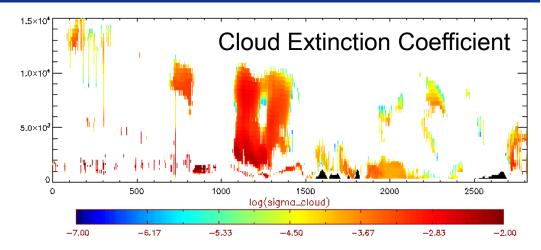


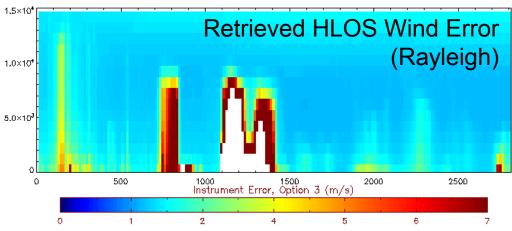




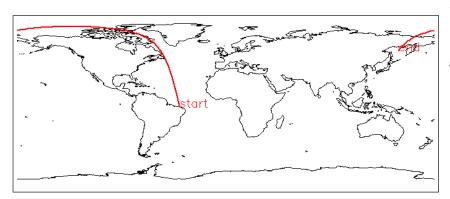
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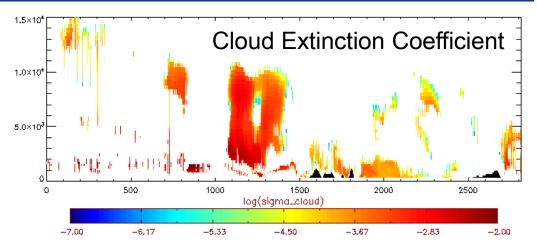


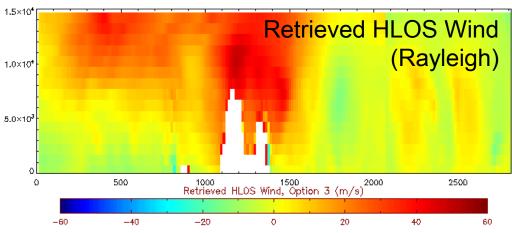




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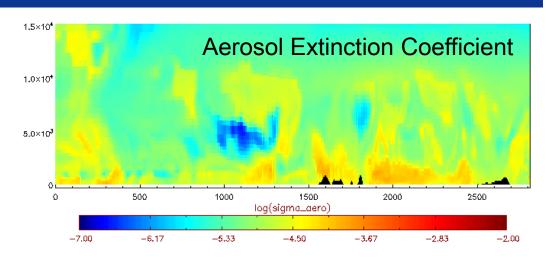


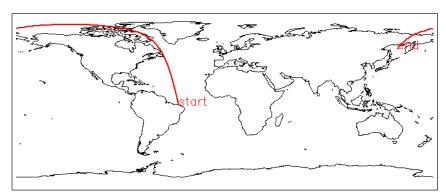


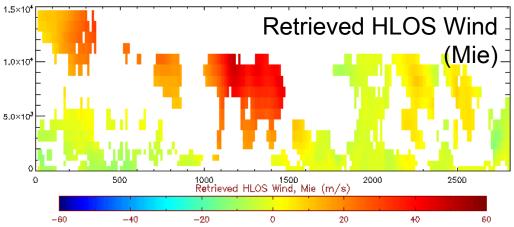


ADM Obs (cont'd)

- cloud and aerosol fields consistent
- Mie channel sampling illustrated





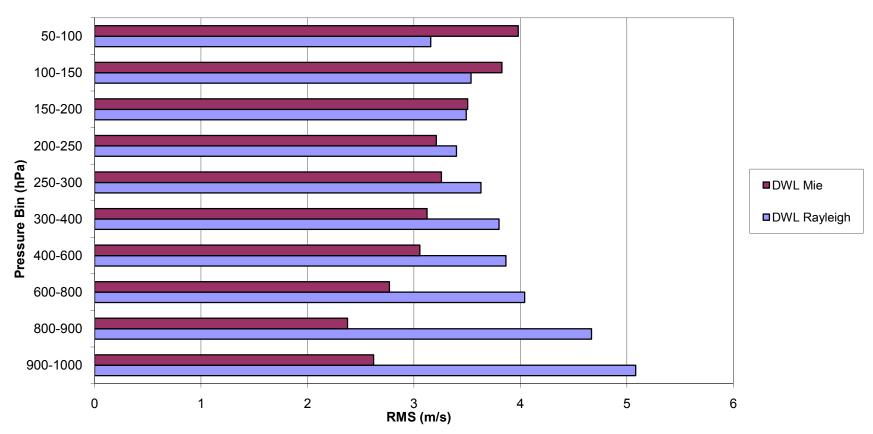


Assimilation and Forecast Impacts

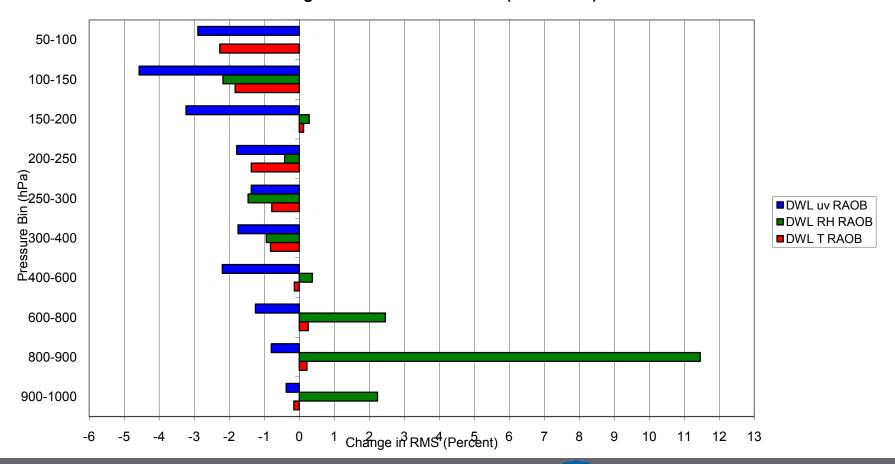
- The results shown are applicable to January of the nature run period
 - DAS Runs every 6 hr with a +/- 3 hr observation window
- Analyses are considered 2x/day (00/12 UTC)
- Forecasts are considered 1x/day (00 UTC)
- Observations included in Control
 - Based on operational data for Jan. 2006
 - Conventional (incl. RAOB & Satellite Winds), TOVS (MSU, AMSU A/B, HIRS), AIRS
- Observations for DWL Experiment
 - Control + ADM

Doppler Wind Lidar O-F RMS vertically

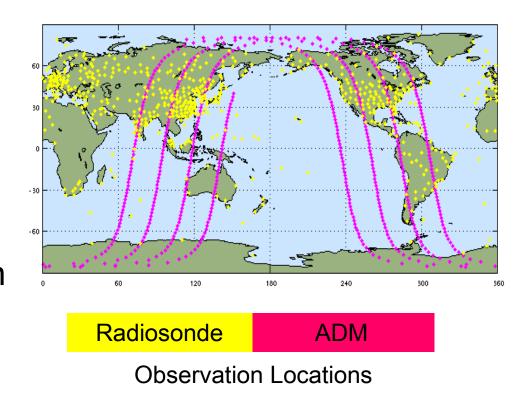
Doppler Wind Lidar RMS (O-F)

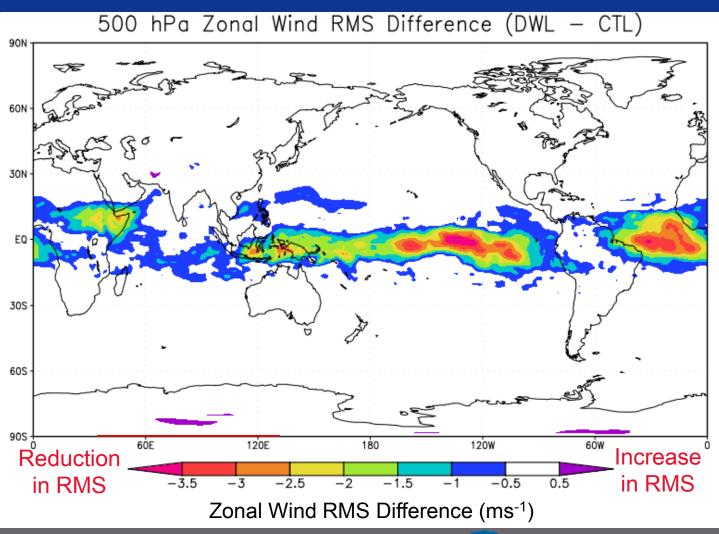


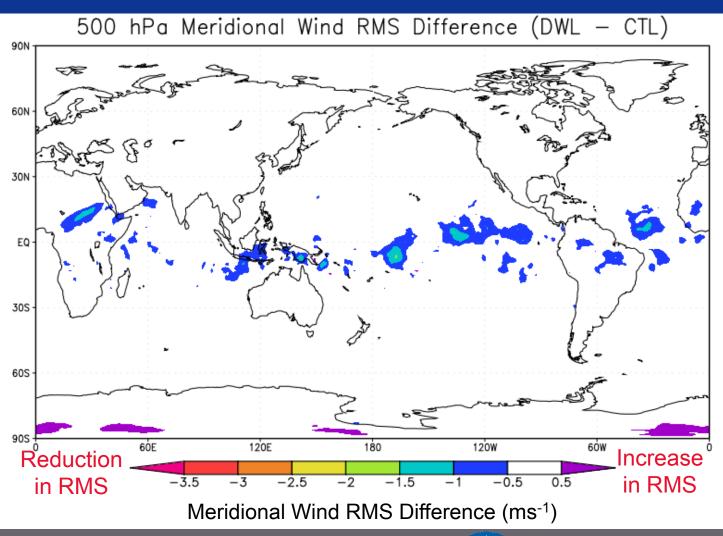
 Change in DWL RMS Vertically for RAOB T, RH, and uv Change in RMS Relative to CTL (DWL - CTL)/CTL

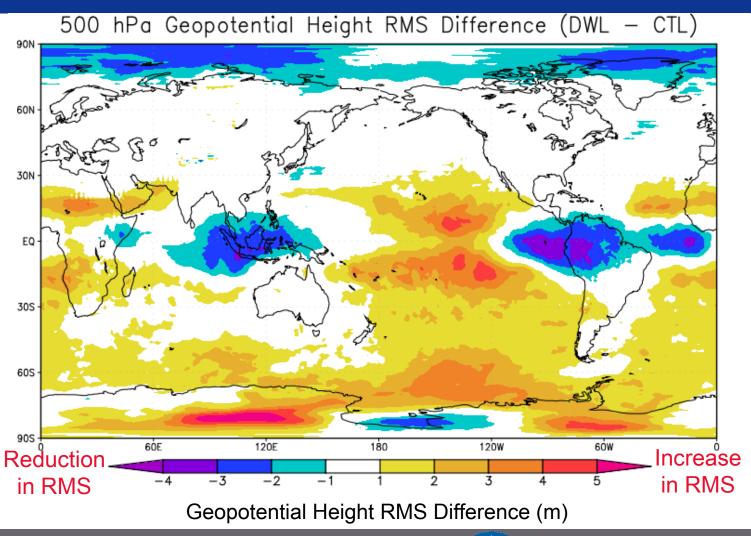


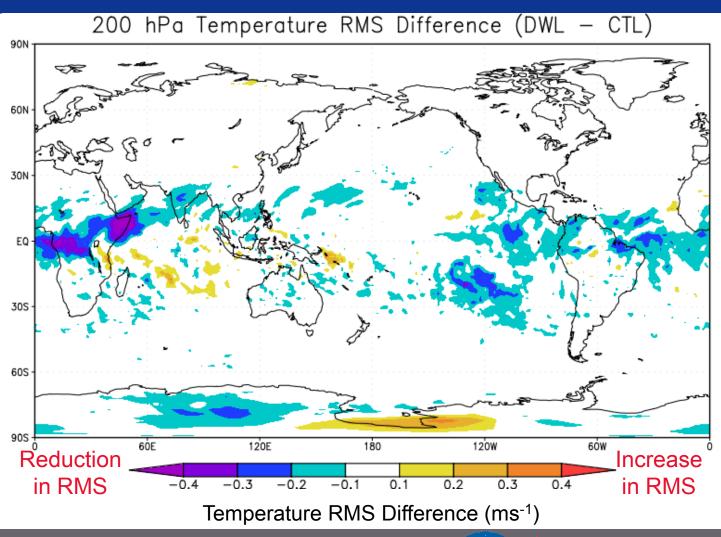
- RAOB observations biased towards Northern Hemisphere midlatitudes
- OSSE framework allows comparison between the analysis and a known truth in analysis space



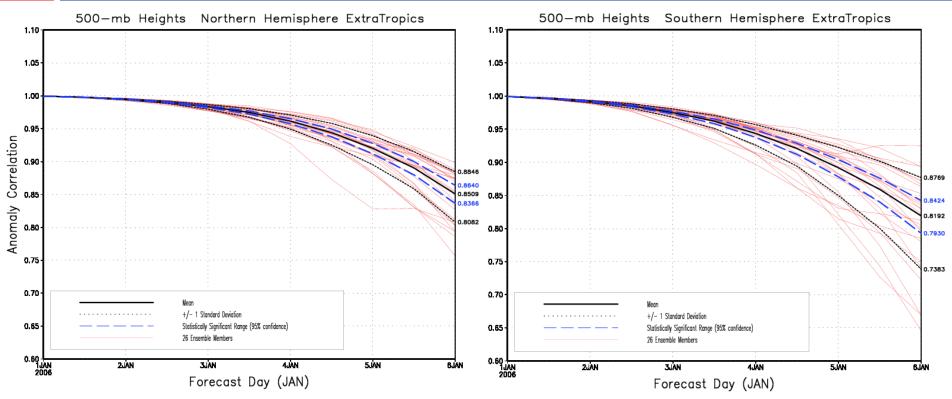








Impact on Forecast



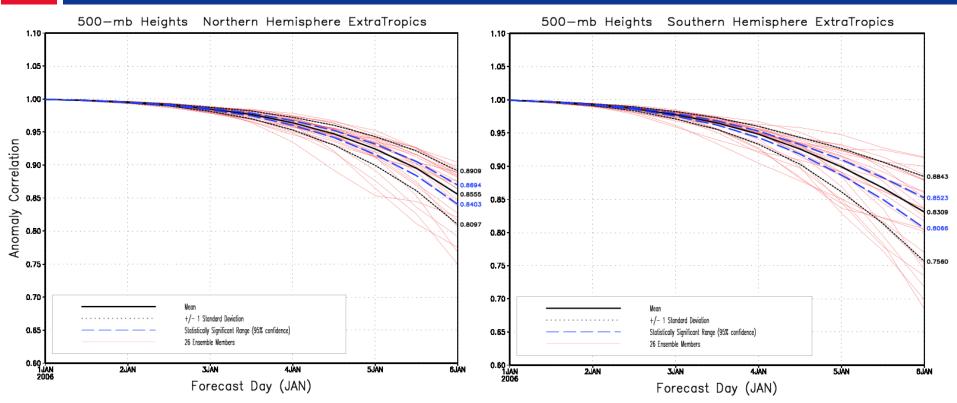
500 hPa Height Anomaly Correlation (CTL)

NH - 0.8509

SH - 0.8192



Impact on Forecast



500 hPa Height Anomaly Correlation (DWL)

NH - 0.8555

SH - 0.8301



Conclusions and Future Efforts

- There are known flaws with the current use of ADM data in the OSSE experiment
 - Observations are too ideal (quality & quantity)
 - Representativeness errors are underspecified
- Expand experiment to increase statistical robustness
- ADM Effort readily translates to studies for 3D-Winds decadal survey mission
- Incorporate L2B processing into GSI system
 - Accelerate ADM/future DWL observation usage into operations
 - Joint Center for Satellite Data Assimilation task

